

# The simplex algorithm (G. Dantzig, 1947)

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# Introduction

The algorithm is structured in two phases

Phase 1. Find a BFS or conclude the LP problem is infeasible

Phase 2. Input: a BFS

Output: an optimal BFS or conclude the problem is unbounded

↳ Phase 2 is used as a subroutine in phase 1. We describe phase 2 first

## Simplex algorithm - Phase 2

Input: a BFS

→ a) Optimality test

b) Compute a new BFS that improves the cost and test of unboundedness

### Optimality test

Reference LP

$$\max_{x \in X} c^T x \quad (\text{LP-5})$$

$$X = \{x \in \mathbb{R}^n : Ax = b, x \geq 0\}$$

Pbl. Let  $B$  be a feasible basis and consider the vertex  $\bar{x}$  given by  $\bar{x}_B = B^{-1}b$  and  $\bar{x}_F = 0$ . Does  $\bar{x}$  verify  $c^T \bar{x} \geq c^T x$ ,  $\forall x \in X$ ?

Parametrization of  $x \in X$  using  $B$

$$Ax = b \Leftrightarrow Bx_B + Fx_F = b \Leftrightarrow x_B = B^{-1}b - B^{-1}Fx_F$$

$\hookrightarrow$  dependent variables

Then

$$x \in X \Leftrightarrow \begin{cases} Ax = b \\ x \geq 0 \end{cases} \Leftrightarrow \begin{cases} B^{-1}b - B^{-1}Fx_F \geq 0 \\ x_F \geq 0 \end{cases} \quad (F)$$

**Rmk.**  $x_F$  are parameters describing all points in  $X$ . If  $x_F = 0$  one gets the BFS, i.e. the vertex associated to  $B$

Cost of a point  $x \in X$

$$\begin{aligned} C^T X &= \underbrace{C_B^T}_{\text{components of the cost associated to B}} X_B + \underbrace{C_F^T}_{\text{components of the cost associated to F}} X_F = C_B^T B^{-1} b - C_B^T B^{-1} F X_F + C_F^T X_F = \\ &= \underbrace{C_B^T B^{-1} b}_z + \underbrace{(C_F^T - C_B^T B^{-1} F)}_{r_F^T} X_F \end{aligned}$$

$z$ : cost of the BFS (where  $x_F = 0$ )

$r_F$ : vector of **reduced costs** associated to  $B$

Lemma (optimality test). Let  $B$  be a feasible basis. If

$$\left. \begin{array}{l} r_F \leq 0 \text{ for a "max" problem} \\ r_F \geq 0 \text{ for a "min" problem} \end{array} \right\} (\bar{I})$$

then, the BFS  $\bar{x}_F = 0, \bar{x}_B = B^{-1} b \geq 0$  is optimal

Rmk. (T) are just sufficient conditions

Corollary. If  $B$  is a feasible **nondegenerate** basis, (T) are necessary and sufficient for optimality

# Simplex Tableau

We associate to an LP the following equations in the variables  $x \in \mathbb{R}^n$  and  $z \in \mathbb{R}$

$$\begin{array}{l} z + c^T x = 0 \\ Ax = b \end{array} \longrightarrow \begin{bmatrix} 1 & c^T \\ 0 & A \end{bmatrix} \begin{bmatrix} z \\ x \end{bmatrix} = \begin{bmatrix} 0 \\ b \end{bmatrix} \quad (L)$$

**Rmk.**  $-z$  stores the cost evaluated at  $x$

Tableau associated to (L)

	$z$	$x_1 \dots x_n$
$0$	$1$	$c^T$
$b$	$0$	$A$

$z$  is already a dependent variable

This column will be not affected by pivoting on elements of  $A$  and it can be omitted

# Simplex tableau

	$x_1 \dots x_n$	
0	$c^T$	
b	A	

← row 0

After putting the tableau in the canonical form w.r.t.  $B$ , one obtains (up to a permutation of row and columns labeled with variables " $x_i$ ")

Opposite of the cost evaluated in the BFS associated to  $B$

	$x_{B,1} \dots x_{B,m}$	$x_{F,1} \dots x_{F,n-m}$
$z$	0	$c_F^T$
$x_{B,1}$ $\vdots$ $x_{B,m}$	$B^{-1}b$	$B^{-1}F$

vector of reduced costs

gives  
 $x_B + B^{-1}F x_F = B^{-1}b$



Test of optimality (tableau form). For a "max" [resp. "min"] problem, all elements in the row 0 and columns  $x_{F_1}, \dots, x_{F_{n-m}}$  must be  $\leq 0$  [resp.  $\geq 0$ ]

### Ex. Product mix

$$\begin{array}{l} \max x^T C \\ Ax = b \\ x \geq 0 \end{array} \quad x^T = [x_1 \quad x_2 \quad s_1 \quad s_2 \quad s_3] \quad C^T = [30 \quad 20 \quad 0 \quad 0 \quad 0]$$

$$A = \begin{bmatrix} 8 & 4 & 1 & 0 & 0 \\ 4 & 6 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 \end{bmatrix} \quad b = \begin{bmatrix} 640 \\ 540 \\ 100 \end{bmatrix}$$

Starting basis for phase 2:  $B = [A_1 \quad A_4 \quad A_5] = \begin{bmatrix} 8 & 0 & 0 \\ 4 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$

Initial simplex tableau

		$x_1$	$x_2$	$s_1$	$s_2$	$s_3$
	0	30	20	0	0	0
$s_1$	640	8	4	1	0	0
$s_2$	540	4	6	0	1	0
$s_3$	100	1	1	0	0	1

→  $s_2$  and  $s_3$  are already dependent variables. To put the tableau in the canonical form w.r.t.  $B$ ,  $x_1$  must enter the basis and  $s_1$  must leave the basis

Pivot operation

		$x_1$	$x_2$	$s_1$	$s_2$	$s_3$
	0	30	20	0	0	0
$s_1$	640	8	4	1	0	0
$s_2$	540	4	6	0	1	0
$s_3$	100	1	1	0	0	1

$AVX = [ \quad 80 \quad 1 \quad \frac{1}{2} \quad \frac{1}{8} \quad 0 \quad 0 ]$

$$- [ 2400 \quad 30 \quad 15 \quad \frac{15}{4} \quad 0 \quad 0 ]$$

$$- [ 320 \quad 4 \quad 2 \quad \frac{1}{2} \quad 0 \quad 0 ]$$

$$- [ 80 \quad 1 \quad \frac{1}{2} \quad \frac{1}{8} \quad 0 \quad 0 ]$$

Tableau in the canonical form w.r.t.  $B$

		$x_1$	$x_2$	$s_1$	$s_2$	$s_3$
	-2400	0	5	$-\frac{15}{4}$	0	0
$x_1$	80	1	$\frac{1}{2}$	$\frac{1}{8}$	0	0
$s_2$	220	0	4	$-\frac{1}{2}$	1	0
$s_3$	20	0	$\frac{1}{2}$	$-\frac{1}{8}$	0	1

Set  $x_B^T = [x_1 \ s_2 \ s_3]$  and  $x_F^T = [x_2 \ s_1]$ . One reads

$$\bar{x}_B = B^{-1}b = \begin{bmatrix} 80 \\ 220 \\ 20 \end{bmatrix} \quad B^{-1}F = \begin{bmatrix} \frac{1}{2} & \frac{1}{8} \\ 4 & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{8} \end{bmatrix}$$

Is  $B$  optimal?  $r_F^T = [5 \ -\frac{15}{4}] \neq 0 \rightarrow$  the basis is not optimal. In particular, increasing  $x_2$  will increase the cost

Computation of a new BFS that improves the cost and test of unboundedness

$B$ : current feasible basis. We assume  $r_F \neq 0$  ( $r_F \neq 0$  for "min" problems)

Then,  $\exists j : r_{F,j} > 0$  ( $r_{F,j} < 0$  for "min" problems)

$\hookrightarrow j$ -th element of  $r_F$

**Rmk.** If  $x_{F,j}$  becomes  $> 0$ , the cost increases (decreases for "min" problems)

**Bland's rule (part I).** If there is more than one index  $j$  such that  $r_{F,j} > 0$ , pick the one associated to the variable  $x_i$  with minimal index  $i$

**Problem:** how much  $x_{F,j}$  can increase?

Assume  $x_{F,3}$  is in the column  $q$  of the tableau. Up to a permutation of the columns one has

		$x_{B,1}$	$\dots$	$x_{B,m}$	$\dots$	$x_{F,3}$	$\dots$
		0	$\dots$	0	*	$\bar{c}_q$	*
$x_{B,1}$	$\bar{b}_1$	1	$\dots$	0	*	$\bar{a}_{1,q}$	*
$\vdots$	$\vdots$					$\vdots$	
$x_{B,m}$	$\bar{b}_m$	0	$\dots$	1		$\bar{a}_{m,q}$	

\* = uninteresting blocks

Keeping  $x_{F,i} = 0 \quad \forall i \neq 3$  one has

← ASSUMPTION

$$\begin{aligned} x_{B,1} &= -x_{F,3} \bar{a}_{1,q} + \bar{b}_1 \\ \vdots & \\ x_{B,m} &= -x_{F,3} \bar{a}_{m,q} + \bar{b}_m \end{aligned}$$

} Note that all uninteresting coeffs have been multiplied by zero

Feasibility of  $x$  implies  $x_{0,i} \geq 0$ ,  $i=1, \dots, m$ . Hence

$$-x_{F,S} \bar{a}_{1,q} + \bar{b}_1 \geq 0$$

$$\vdots$$
$$-x_{F,S} \bar{a}_{m,q} + \bar{b}_m \geq 0$$

Case I (unboundedness). All  $\bar{a}_{1,q}, \dots, \bar{a}_{m,q}$  are  $\leq 0$ . Since  $x_{F,S}$  can grow arbitrarily, the LP problem is unbounded

Case II (find the most restrictive constraint). Each inequality with  $\bar{a}_{i,q} > 0$  puts an upper bound to  $x_{F,S}$

Let

$$\frac{\bar{b}_p}{\bar{a}_{p,q}} = \min_{i: \bar{a}_{i,q} > 0} \frac{\bar{b}_i}{\bar{a}_{i,q}}$$

Bland's rule (part II). If there are multiple indices  $i$  for which the minimum ratio is achieved, pick up the one corresponding to the basic variable  $x_i$  with minimal index  $i$ .

The most restrictive inequality is

$$x_{B,p} - x_{F,s} \bar{a}_{p,q} + \bar{b}_p \geq 0$$

Setting  $x_{F,j} = \frac{\bar{b}_p}{a_{p,q}}$ , then

- the cost is increased by  $\bar{c}_q \cdot \frac{\bar{b}_p}{a_{p,q}}$  → increment in  $x_{F,j}$  from zero
- $x_{B,p}$  becomes zero

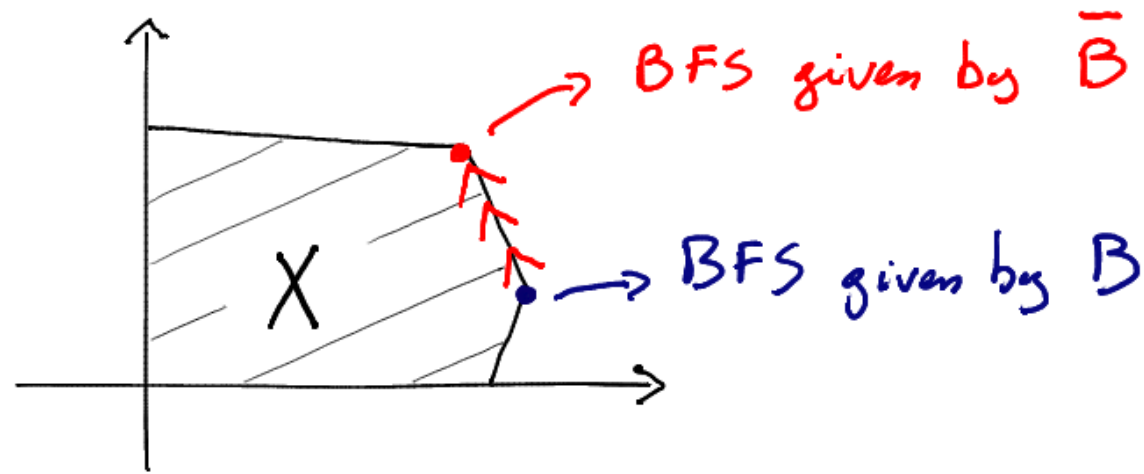
Therefore,  $x_{F,j}$  enters the basis and  $x_{B,p}$  leaves the basis → a single pivoting on the element in the pivot row  $x_{B,p}$  and pivot column  $x_{F,j}$ .

**Rmk.** The minimal **positive** ( $\geq 0$ ) ratio defines the BV that leaves the basis.

The new basis  $\bar{B}$  is obtained by replacing the column of  $B$  associated to  $x_{B,p}$  with the column  $A_q$ . **Problem:** is  $\bar{B}$  feasible?



Lemma.  $\bar{B}$  is a *feasible basis*. If the vertices associated to  $B$  and  $\bar{B}$  are different, they are adjacent



## Ex. Product mix (c.t.d)

$$\begin{aligned} \max x^T C^T & \quad x^T = [x_1 \quad x_2 \quad s_1 \quad s_2 \quad s_3] \quad C^T = [30 \quad 20 \quad 0 \quad 0 \quad 0] \\ Ax = b & \\ x \geq 0 & \end{aligned}$$

$$A = \begin{bmatrix} 8 & 4 & 1 & 0 & 0 \\ 4 & 6 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 \end{bmatrix} \quad b = \begin{bmatrix} 640 \\ 540 \\ 100 \end{bmatrix}$$

Starting basis for phase 2:  $B = [A_1 \quad A_4 \quad A_5]$

Tableau in the canonical form w.r.t. B  $\longrightarrow$

		$x_1$	$x_2$	$s_1$	$s_2$	$s_3$
	-2400	0	5	$-\frac{13}{4}$	0	0
$x_1$	80	1	$\frac{1}{2}$	$\frac{1}{8}$	0	0
$s_2$	220	0	4	$-\frac{1}{2}$	1	0
$s_3$	20	0	$\frac{1}{2}$	$-\frac{1}{8}$	0	1

## Phase 2 - Iteration 1

		$x_1$	$x_2$	$s_1$	$s_2$	$s_3$
	-2400	0	5	$-\frac{15}{4}$	0	0
$x_1$	80	1	$\frac{1}{2}$	$\frac{1}{8}$	0	0
$s_2$	220	0	4	$-\frac{1}{2}$	1	0
$s_3$	20	0	$\frac{1}{2}$	$-\frac{1}{8}$	0	1

Optimality Test.  $c_F^T = [5 \ -\frac{15}{4}] \neq 0 \rightarrow$  The BFS is not optimal

Choice of the NBV that enters the basis

$x_3$  with associated reduced cost  $> 0$  and minimum index  $J$

$\hookrightarrow x_2$  becomes basic  $\rightarrow$  pivot column = column " $x_2$ "

		$x_1$	$x_2$	$s_1$	$s_2$	$s_3$
	-2400	0	5	$-\frac{13}{4}$	0	0
$x_1$	80	1	$\frac{1}{2}$	$\frac{1}{8}$	0	0
$s_2$	220	0	4	$-\frac{1}{2}$	1	0
$s_3$	20	0	$\frac{1}{2}$	$-\frac{1}{8}$	0	1

Choice of the BV that leaves the basis and test of unboundedness

Ratios:

$$\frac{80}{\frac{1}{2}} = 160$$

$$\frac{220}{4} = 55$$

$$\frac{20}{\frac{1}{2}} = 40 \rightarrow \text{minimal positive ratio. } s_3 \text{ leaves the basis and defines the pivot row}$$

Pivoting on the pivot element (at the intersection of the pivot row and column)

		$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	
	-2400	0	5	$-\frac{15}{4}$	0	0	- [200 0 5 $-\frac{5}{4}$ 0 10]
$x_1$	80	1	$\frac{1}{2}$	$-\frac{1}{8}$	0	0	- [20 0 $\frac{1}{2}$ $-\frac{1}{8}$ 0 1]
$s_2$	220	0	4	$-\frac{1}{2}$	1	0	- [160 0 4 -1 0 8]
$s_3$	20	0	$\frac{1}{2}$	$-\frac{1}{8}$	0	1	

AUX = [40 0 1  $-\frac{1}{4}$  0 2]

		$x_1$	$x_2$	$s_1$	$s_2$	$s_3$
	-2600	0	0	$-\frac{5}{2}$	0	-10
$x_1$	60	1	0	$\frac{1}{4}$	0	-1
$s_2$	60	0	0	$\frac{1}{2}$	1	-8
$x_2$	40	0	1	$-\frac{1}{4}$	0	2

## Phase 2 - Iteration 2

		$x_1$	$x_2$	$s_1$	$s_2$	$s_3$
	-2600	0	0	$-\frac{5}{2}$	0	-10
$x_1$	60	1	0	$\frac{1}{4}$	0	-1
$s_2$	60	0	0	$\frac{1}{2}$	1	-8
$x_2$	40	0	1	$-\frac{1}{4}$	0	2

Optimality test.  $r_F^T = \left[ -\frac{5}{2} \quad -10 \right] \leq 0 \rightarrow$  The BFS is optimal and the algorithm stops.

Reading the results from the final tableau

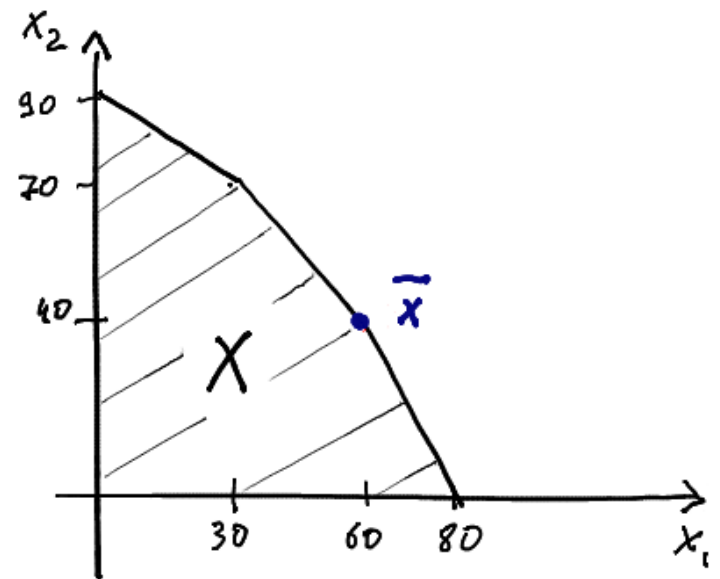
		$x_1$	$x_2$	$s_1$	$s_2$	$s_3$
	$-2600$	0	0	$-\frac{5}{2}$	0	-10
$x_1$	60	1	0	$\frac{1}{4}$	0	-1
$s_2$	60	0	0	$\frac{1}{2}$	1	-8
$x_2$	40	0	1	$-\frac{1}{4}$	0	2

Optimal solution  $\bar{x}$  given by

$$\bar{x}_D^T = [x_1 \ s_2 \ x_2] = [60 \ 60 \ 40]$$

$$\bar{x}_F^T = [s_1 \ s_3] = [0 \ 0]$$

Optimal cost: 2600



## Ex. @ home

Consider the LP problem

$$\max x_1 + x_2$$

$$6x_1 + 4x_2 + x_3 = 24$$

$$3x_1 - 2x_2 + x_4 = 6$$

$$x_1, \dots, x_4 \geq 0$$

Verify that the basis associated to the variables  $x_1$  and  $x_2$  is feasible and, starting from this basis, solve the problem running phase 2 of the simplex algorithm.